





3214

2143

1/5

0

Matrix of high-order marginals Block-diagonal sum of coefficients Instead of storing marginals, only store this minimal set of coefficients (from which marginals can be reconstructed)

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The Fourier view

- Our minimal set of coefficients can be interpreted as a generalized Fourier basis!! [Diaconis, `88]
- General picture provided by group theory:
- The space of functions on a group can be decomposed into Fourier components with the familiar properties: Orthogonality, Plancherel's theorem, Convolution theorem, ...
- For permutations, simple marginals are "low-frequency": • 1st order marginals are "lowest-frequency" basis functions
- 2nd order (unordered) marginals are 2nd lowestfrequency basis functions

Group representations

- The analog of sinusoidal basis functions for groups are called group representations
- A group representation, ρ of a group G is a map from G to the set of d₀x d₀ matrices such that for all σ₁,σ₂∈ G:
 - $\rho(\sigma_1 \sigma_2) = \rho(\sigma_1) \cdot \rho(\sigma_2)$

This is like:
$$e^{i\theta_1} \cdot e^{i\theta_2} = e^{i(\theta_1 + \theta_2)}$$

- Example: The trivial representation is defined by: $\tau_0(\sigma) = 1, \quad \forall \sigma \in G$
- The trivial representation is the constant basis function and captures the normalization constant of a distribution in the generalized Fourier theory

The Fourier Transform

- Each matrix entry of a representation is its own basis
- function! Define the Fourier Transform of a function f, at the **representation** ρ to be the **projection** of f onto the basis given by ρ :

$$f_{\sigma} = \sum_{\sigma \in G} f(\sigma) \rho(\sigma)$$

- Note that: Generalized Fourier transforms are matrix-valued! • And are **functions of representation** (instead of frequency)
- For most ρ , we end up with an overcomplete basis But... there are only two ways in which linear dependencies can appear in group representations

Example: 1st order representation



- Example: $\tau_1([123]) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \quad \tau_1([213]) = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad \tau_1([132]) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ 0 0 1 $0 \ 0 \ 1$ 0 1 0 $\begin{bmatrix} 0 & 1 & 0 \end{bmatrix}$ $\begin{bmatrix} 0 & 0 & 1 \end{bmatrix}$ $\tau_1([231]) = \begin{vmatrix} 1 & 0 & 0 \end{vmatrix} \quad \tau_1([312]) = \begin{vmatrix} 0 & 0 & 1 \end{vmatrix}$ $\tau_1([321]) = \begin{bmatrix} 0 & 1 & 0 \end{bmatrix}$ 1 0 0 $1 \ 0 \ 0$ 0 1 0
- The Fourier transform of a distribution P, at the 1st order permutation representation is exactly the 1st order matrix of marginal probabilities of P!

Two sources of overcompleteness
1. Can combine two representations ρ_1 , ρ_2 to get a new representation $\rho_1 \oplus \rho_2$ (called the direct sum representation): $\rho_1 \oplus \rho_2 = \left[\frac{\rho_1 \ 0}{0 \ \rho_2}\right]$
Example: (direct sum of two trivial representations) $ au_0 \oplus au_0(\sigma) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \forall \sigma \in G$
2. Given a representation ρ_1 , can "change the basis" to get a new representation by conjugating with an invertible matrix, C: $\rho_2(\sigma) = C^{-1} \cdot \rho_1(\sigma) \cdot C$

 ρ_1 and ρ_2 are called equivalent representations



• $P(z=green \mid \sigma(Alice)=Track \mathbf{1}) = 9/10$ ("If Alice is at Track 1, then we see green at Track 1 with probability **9/10**")



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Minimization can be written as an efficient Quadratic

program!

• Minimize the distance to the Marginal Polytope in the Fourier domain by using the Plancherel theorem: $\sum (f(\sigma) - g(\sigma))^2 = \frac{1}{|G|} \sum d_{\rho_k} \operatorname{Tr} \left(\left(\hat{f}_{\rho_k} - \hat{g}_{\rho_k} \right)^T \cdot \left(\hat{f}_{\rho_k} - \hat{g}_{\rho_k} \right) \right)$

projecting to the marginal polytope

and simulated data

Evaluated approach on real camera network application